DEVELOPMENT OF A DIDACTIC WORKBENCH USING REAL-TIME LUI MENT UF A DIDE
ADIME OVERNATOD ! MONITORING SYSTEM FOR TEACHING OF PHOTOVOLTAIC SYSTEMS

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Abstract – **This paper presents the deployment of a didactic workbench intended to support theoretical and practical studies addressed in subjects of undergraduate and postgraduate electrical engineering courses involving photovoltaic (PV) systems. The proposed system operates in real-time and is composed of a computational graphic interface operating in conjunction with a double-stage PV system connected to the power grid. Besides the PV array, the PV system consists of a step-up DC-DC converter, intended to track the maximum power point, and a current-controlled full-bridge inverter, intended to inject the energy produced by the PV array into the grid. The monitoring system allows to perform the following tasks: i. assist the performance evaluation of maximum power point tracking techniques tied to projects; ii. visualize the measured PV array magnitudes (voltage, current and power), as well as the estimated ones calculated from the PV array mathematical model and from the real measured values of solar irradiation and temperature; iii. analyze electric power quality indicators, based on the grid voltage and current magnitudes, and others. Experimental results are presented with the objective of testing and evaluating the versatility of the proposed didactic workbench applied in an educational environment.**

Keywords – **Didactic Workbench, Educational PV System, Graphical User Interface, Real-time Monitoring.**

I. INTRODUCTION

In the last few decades, the use of alternative energy sources based on renewable energy sources (RES) has been increasing due to the growing demand for electricity, as well as the real need to replace non-renewable energy sources based on fossil fuels, which carry the disadvantage of causing considerable environmental impacts [1], [2]. Within this context, solar energy [1]-[3] and wind energy [4], [5] have been consolidated as the main RES used for electricity generation. Among the various forms of electric energy production from solar energy, photovoltaic (PV) panels have been widely used and diffused in distributed generation systems [6], [7].

Considering an educational environment, several topics and/or subjects that are being discussed and taught in undergraduate and postgraduate electrical engineering courses

are linked to some technological applications involving RES, in particular to PV systems, for instance [8]-[12].

Thus, inserted in a teaching context, discussions about PV systems supported by computational tools can stablish more dynamic and accessible interaction with students, as well as can accelerate the teaching-learning process [13]-[16]. Furthermore, theoretical concepts can be more easily assimilated and consolidated, as well as the development of engineering activities tied to projects can be optimized and/or validated [17], [18].

The main contribution of this paper is the deployment of a didactic workbench intended to support theoretical and practical studies addressed in subjects of undergraduate and postgraduate electrical engineering courses involving PV systems. The proposed system integrates a real-time monitoring system (RTMS) with a PV system connected to the power grid resulting in a versatile teaching platform.

The referred educational tool can perform the following tasks: 1) assist the performance evaluation of maximum power point tracking (MPPT) techniques tied to projects; 2) validate the PV cell modeling and estimate parameters of the PV array; 3) detect the power generated by the PV array and the power injected into the grid; 4) evaluate power quality indicators, such as power factor (PF) and total harmonic distortion (THD) involving the current injected into the grid; 5) visualize, in real-time, quantities of voltage and current, trace the PV array characteristic curves $(I_{PV} x V_{PV}$ and $P_{PV} x V_{PV}$, and others.

The interaction between the RTMS and the student is achieved through a graphical user interface (GUI), which can help the development the mentioned tasks [13], [19].

Furthermore, once the educational platform developed is conceived by means the use of static converters, such as the step-up DC-DC converter (quadratic boost converter) and the single-phase full-bridge voltage-source inverter (VSI), some subjects related to power electronics concepts can also be widely explored, especially those related to the control system and design and modelling of static converters [20].

This paper is organized as follows: Section 2 presents the PV system characteristics involving the PV cell model, the power converters control systems and the MPPT technique. The PV system integrated to the didactic workbench is described in Section 3. Experimental results are shown in Section 4 to evaluate the versatility of the graphical user interface and the real-time monitoring system. The application of the didactic workbench for educational purposes is shown in Section 5. Section 6 presents the conclusions.

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Fig. 1. Complete scheme of the real-time monitoring system (RTMS).

II. DESCRIPTION OF THE DIDACTIC WORKBENCH

The comprehensive scheme of the proposed didactic workbench is shown in Figure 1. It comprises a PV panel, a DC-DC quadratic boost converter followed by a single-phase full-bridge VSI. The experimental set uses a DSC (Digital Signal Controller), where the MPPT technique, the phaselocked loop (PLL) scheme, and the control loops of the inverter and the DC-DC converter are embedded. The data acquisition system DAQ USB-6222 (*National Instruments*) is responsible for acquiring the system signals (PV system and grid quantities, solar irradiation and temperature) and to perform the communication between USB and RTMS. In addition, LabVIEW software (*National Instruments*) is employed to operate integrated with the hardware (DAQ) and visualize all the aspects of the application by means of a graphical programming.

Since the GUI was developed based on this platform, it is possible to visualize, for example, the characteristic curves of the PV array, such as current-voltage $(I_{PV}xV_{PV})$ and powervoltage ($P_{PV}xV_{PV}$), which are traced using the mathematical model of the PV cell and the measured signals as solar irradiation and temperature. Furthermore, the voltage and current at the PV array terminals, the power drained from the PV panel, the grid voltage and the current injected into the grid can also be viewed. As a result, the performance of the adopted MPPT technique can be evaluated, allowing to check if the system is extracting the maximum power the PV array is able of generating.

III. DESCRIPTION OF THE PV SYSTEM

In this section is described the model that represents the PV cell, as well as the power circuits that compose the PV system integrated to the didactic workbench.

A. PV Cell Mathematical Model

The equivalent electric circuit that represents the model of a PV cell adopted in this paper is presented to carry out the study and implementation of the PV system. The PV cell mathematical model is used to create the PV array characteristic curves $I_{PV} \times V_{PV}$ and $P_{PV} \times V_{PV}$ from the information obtained by means of the solar irradiation and temperature. Therefore, it is possible to check if the actual values of the monitored quantities of the PV array, including voltage V_{PV} , current I_{PV} and power P_{PV} , correspond to the values estimated and obtained from the model.

The equivalent electric of the PV cell circuit adopted in this paper is shown in Figure 2 [21]-[23], where I_{ph} is the photocurrent; I represents the output current of the PV cell; V is the output voltage of the cell. In addition, the series and parallel resistances are represented by R_s and R_n , respectively.

Fig. 2. Equivalent circuit of the photovoltaic cell.

The magnitudes I and I_{ph} , the reverse saturation current I_r , the reverse saturation current $(I_{r(STC})$ in STC (Standard Test Conditions), the PV module voltage (V_{PV}) and the open circuit voltage of the photovoltaic array (V_{OC}) can be identified by (1), (2), (3), (4), (5) and (6) [22], respectively, where *q* is the electron charge; η is the ideality factor of the p-n junction; k is the Boltzmann's constant; T_r is the nominal temperature in Kelvin; I_{SC} is the short-circuit current in STC (T_r = 298 K and $G = 1000$ W/m²); α is the temperature coefficient; E_g is the band energy (1.1 eV); $V_{OC, c}$ is the open circuit voltage of the photovoltaic cell; and N_s is the number of photovoltaic cells.

$$
I = I_{ph} - I_r \left[e^{q\frac{V + IR_s}{\eta kT}} - 1 \right] - \frac{V + IR_s}{R_p} \tag{1}
$$

$$
I_{ph} = [I_{SC} + \alpha (T - T_r)] \frac{G}{1000}
$$
 (2)

$$
I_r = I_{r(STC)} \left(\frac{T}{T_r}\right)^3 e^{\left[\frac{qE_g}{\eta k} \left(\frac{1}{T_r} - \frac{1}{T}\right)\right]}
$$
(3)

$$
I_{r(STC)} = \frac{I_{SC} - \frac{V}{R_p}}{e^{\frac{qV_{OCC}}{\eta kT_r}} - 1}
$$
(4)

$$
V_{PV} = V N_s \tag{5}
$$

$$
V_{OC} = V_{OC_c} N_s \tag{6}
$$

To solve the set of equations from (1) to (6), a numerical method was used. For that reason, the current of the cell for a given operation point is obtained by adopting the Newton-Raphson method represented by (7) , where *n* is the nth iteration of the algorithm and $f'(I_n)$ is the derivative of the current corresponding to iteration *n*. Thus, (8) and (9) determine the current of the PV cell for a given iteration.

$$
I_{n+1} = I_n - \frac{f(I_n)}{f'(I_n)}
$$
\n(7)

$$
f(I_n) = I_{ph} - I_n - I_r \left[e^{q \frac{V + I_n R_s}{\eta kT}} - 1 \right] - \frac{V + I_n R_s}{R_p}
$$
(8)

$$
f'(I_n) = -1 - I_r e^{q\frac{V + I_n R_s}{\eta kT}} \frac{qI_n R_s}{\eta kT} - \frac{R_s}{R_p}
$$
 (9)

Known the PV mathematical model and considering the PV parameters, the characteristic curves $I_{PV} \times V_{PV}$ and $P_{PV} \times V_{PV}$ can be obtained, as shown in Figures 3a and 3b, respectively.

Table I presents the parameters used in the mathematical model of the PV cell, such as *q*, *k*, *α*, *Eg*, *η*, *Rs* and *Rp*. Additional PV parameters, such as the maximum power of the PV array *Pmax*=*PMPP*, voltage *VMPP* and current *IMPP* at the maximum power point, open circuit voltage V_{OC} , short circuit current *I_{SC}*, number of cells *Ns* and current temperature coefficient *α* were extracted from de PV manufacturer data (PV module SW245 – SolarWorld).

As can be noted in Figures 3c and 3d, according to the variations of solar irradiation and temperature, the maximum power point (P_{MPP}) varies, too.

B. DC-AC Full-bridge Converter

The single-phase full-bridge VSI is used to connect the PV system to the grid as shown in Figure 1, while its equivalent circuit is shown in Figure 4, where v_s is the mains voltage; v_{DC} is the DC-bus voltage; *d* is the duty cycle of the PWM inverter; and L_f and R_{Lf} represent the inductance and internal resistance of the filtering inductor, respectively.

Fig. 3. PV array curves: (a) characteristic curve $I_{PV} \times V_{PV}$, (b) characteristic curve $P_{PV} \times V_{PV}$, (c) $P_{PV} \times V_{PV}$ curve with solar irradiation variation, (d) $P_{PV} \times V_{PV}$ curve with temperature variation.

The full-bridge inverter topology was chosen due to the possibility to employ the pulse width modulation (PWM) with a unipolar (three-level) voltage switching. This PWM technique has advantage when compared to the PWM with bipolar voltage switching, because it effectively doubling the switching frequency that appears in the harmonic spectrum of the output inverter voltage waveform. On the other hand, fullbridge inverter topology driven by unipolar voltage switching results in the increase of PV array common-mode current due to the variations of the common-mode voltage of the fullbridge inverter [24].

Fig. 4. DC-AC full-bridge converter: equivalent electric circuit of the grid-tied inverter

Applying the small-signal modeling [20] and neglecting the disturbances in the grid voltage and in the DC-bus, the transfer function that relates the input current (i_s) and the duty cycle (d) of the PWM inverter can be found as:

$$
G_{i_{s}d}(s) = \frac{\hat{i}_{s}(s)}{\hat{d}(s)} = \frac{V_{DC}}{L_{f}s + R_{Lf}}.
$$
 (10)

Figure 5 presents the control system block diagram of the inverter current and the DC-bus voltage, where K_{pi} and K_{li} represent the proportional-integrative (PI) gains of the current controller; K_{Pv} and K_{lv} are the PI gains of the DC-bus voltage controller; and K_{PWM} represents the static gain of the pulse width modulator, which is calculated considering the inverse of the peak value of the triangular carrier [20].

Fig. 5. DC-AC full-bridge converter: control system block diagram of the inverter current and the DC-bus voltage.

The DC-bus PI controller output signal, defined by i_{DC} maintains the DC-bus voltage constant, as well as to control the amplitude of the current i_s injected into the grid [25], while a single-phase PLL system is used to obtain the sinusoidal reference current (i_s^*) of the current controller synchronized with the grid voltage [26].

C. Quadratic Boost Converter

The use of the quadratic boost converter is justified due to the need to obtain a high voltage gain in the converter $(G_{b,q} \cong$ 7), since the voltage of a single PV panel in MPPT ($V_{MPP} \cong$ 30.8V) must be increased to $V_{DC} = 220$ V (DC-bus inverter). The quadratic boost converter is also controlled to track the maximum point of power of the PV array, to follow the voltage reference provided by the MPPT algorithm.

From the circuit shown in Figure 6a, the model of the quadratic boost converter working to reach the MPPT can be obtained, where R_{PV} is the output impedance of the PV array in STC (G=1000W/m² and T=25°C); C_1 and C_2 are the filter capacitances; L_1 and L_2 are the filter inductances of the converter, while R_{L1} and R_{L2} are their respective internal resistances. The output voltage of the converter is considered constant, since it is controlled by the DC-bus voltage controller shown in Figure 5. The equivalent circuits representing the operating stages of the DC-DC converter are shown Figure 6b (S_h switch turned on), and Figure 6c (S_h) switch turned off).

Figure 6d shows the block diagram of the multi-loop control of the quadratic boost converter, which is composed of an inner current control loop and an outer voltage control loop.

Due to the presence of resonance peaks, caused by the LC filter, the use of a single PI voltage controller can become the closed-loop control system unstable. Thus, to overcome this problem and contribute to attenuate the resonance peaks, it is employed the inner current control loop whose PI controller must be tuned in frequencies higher than the frequencies in which the resonance peaks occur. Therefore, by tuning the outer PI voltage controller in frequencies lower than the resonant ones, it is possible to guarantee the stability of the system.

Through the application of small-signal modeling, the transfer functions of the two control loops of the converter are obtained, namely: the external voltage loop $G_{\nu b_i}(s)$ and the internal current loop $G_{ib_d}(s)$, which are respectively given by:

Fig. 6. Electrical circuit and operating stages of the quadratic boost converter: (a) model of the quadratic boost converter; (b) first operating stage (switch on), (c) second operating stage (switch off), (d) block diagram of the current and voltage control loops.

$$
G_{v b_i}(s) = \frac{\hat{v}_{C_1}(s)}{\hat{\iota}_{L_1}(s)} = -\frac{R_{p v}}{C_1 R_{p v} s + 1} \tag{11}
$$

$$
G_{ib_d}(s) = \frac{\hat{\iota}_{L_1}(s)}{\hat{d}_b(s)} = \frac{a_0 s^3 + a_1 s^2 + a_2 s + a_3}{b_0 s^4 + b_1 s^3 + b_2 s^2 + b_3 s + b_4} \tag{12}
$$

where:

$$
a_0 = C_1 C_2 L_2 V_{C_2};
$$

\n
$$
a_1 = C_1 D' I_{L1} L_2 + C_1 C_2 R_{L_2} V_{C_2} + C_2 L_2 R_{PV} V_{C_2};
$$

\n
$$
a_2 = C_1 V_{C_2} + C_1 D' V_{cc} + C_1 D' I_{L1} L_2 R_{L2} + D' I_{L1} L_2 R_{PV} + C_2 R_{L_2} R_{PV} V_{C_2};
$$

\n
$$
a_3 = R_{PV} V_{C2} + D' R_{PV} V_{cc} + D' I_{L1} R_{L_2} R_{PV};
$$

\n
$$
b_0 = C_1 C_2 L_1 L_2;
$$

\n
$$
b_1 = C_1 C_2 L_1 R_{L_2} + C_1 C_2 L_2 R_{L_1} + C_2 L_1 L_2 R_{PV};
$$

\n
$$
b_2 = C_1 L_2 D'^2 + C_1 L_1 + C_2 L_2 + C_1 C_2 R_{L_1} R_{L_2} + C_2 L_2 R_{L_1} R_{PV};
$$

\n
$$
b_3 = C_1 R_{L_1} + C_2 R_{L_2} + L_1 R_{PV} + C_1 D'^2 R_{L_2} + D'^2 L_2 R_{PV} + C_2 R_{L_1} R_{L_2} R_{PV};
$$

\n
$$
b_4 = R_{L_2} R_{PV} D'^2 + R_{L_1} R_{PV} + 1.
$$

The quantity V_c , represents the specified average voltage in the capacitor C_2 ; I_{L1} is the specified average current of the inductor L_1 ; and $D' = 1 - D$, where D is the converter duty cycle

Figure 6d shows the input voltage control system $v_{C_1}(t)$ of the quadratic boost converter, where the internal current control loop in the inductor L_1 and the external voltage control loop (C_1) are represented. This loop must ensure that the voltage across the capacitor C_1 follows the reference set by the MPPT algorithm (V_{MPP}^*) . The gains K_{Pvb} and K_{Ivb} represent, respectively, the proportional and integral gains of the voltage controller, while K_{Pih} and K_{Iih} represent the PI gains of the current control loop.

D. MPPT Algorithm

In spite of all the advantages presented by the generation of electric energy by the photovoltaic panel, the efficiency of the conversion of solar energy to electric energy is currently low, and the initial cost for its implementation is still considered high. Therefore, it is necessary to apply the MPPT techniques in order to obtain the best use of electric energy produced by a PV array. Nonetheless, there is only one point of maximum power (P_{MPP}) to be reached, which varies according to climatic conditions, such as solar irradiation and temperature.

The MPPT based on Perturb and Observe (P&O) technique [1], [27] was adopted in the present paper to achieve the MPP of a PV array that is composed of a unique PV panel. The flowchart of the P&O-based MPPT is shown in Figure 7.

The time between the changes in the PV panel voltage references obtained from the MPPT based on P&O algorithm must be necessarily higher than the set-up time of the control system. If this condition is not met, the MPPT algorithm can operate incorrectly, due to the PV array voltage will still be changing at the time in which a new PV voltage reference is set by the MPPT algorithm. Thus, to ensure the PV voltage controller being fast enough, its crossover frequency at 0dB was selected at three times higher than the MPPT frequency, as can be observed in Table II (f_S_{MPPT} = 5 Hz) and Table III $(\omega_{cub} = 96.66 \text{ rad/s}).$

Fig. 7. Flowchart of the MPPT based on P&O technique.

IV. EXPERIMENTAL RESULTS

In this section, experimental results are presented with the objective of evaluating the operation of the didactic workbench. (educational platform), based on the scheme shown in Figure 1.

The full-bridge inverter was built using IGBT SK40GB123 (Semikron) power modules, whereas in the quadratic boost converter the discrete IGBT IRGP50B60PD1PBF and diodes HFA30PB120PBF (*Vishay*) were used. The MPPT and PLL algorithms, as well as the converters control loops were embedded into the digital signal controller TMS320F28335 (*Texas Instruments*). The LA 55-P and LV 25-P (*LEM*) transducers were used in measurements of current and voltage quantities, respectively. For sensing the solar irradiation, the pyrometer ML-01 EKO (*Eko Instruments*) was used, while the temperature of the PV array was measured through the surface temperature sensor PT-100 SFCSD-50 (*Kimo Instruments*). Finally, monitored signals and communication with the LabVIEW software were acquired by means of a DAQ NI USB-6221 (*National Instruments*) data acquisition board.

The prototype parameters are listed in Table II, while the design specifications, as well as the gains of the PI controllers (DC/DC a DC/AC converters) are presented in Table III.

As aforementioned, the GUI presented in this paper was developed using LabVIEW software. It is divided in six interactive user interfaces (INT), as shown in Figures 8 and 9.

Figure 8a shows the interface 1 (INT1), called "Settings", where the user must enter the PV array parameters at STC, such as $P_{max} = P_{MPP}$, V_{MPP} , I_{MPP} , V_{OC} , I_{SC} , N_s , G and T , as well as the sampling frequency and sample rate settings of the DAQ NI USB-6221. Additional parameters that compose the PV cell model, such as *q*, *k*, *α*, *Eg*, and *η* have been previously stored in the GUI library as default values.

Interface 2 (INT2), shown in Figure 8b, represents a subinterface of INT1. In this interface, called "Adjustments of series and parallel resistances of the PV cell model", the user can adjust the values of R_s and R_p that refer to the model of the PV cell shown in Figure 2. This procedure must be performed to meet the specification parameters of the PV module shown in Table I.

It can be noted from INT2 (Figure 8b), after the adjusting R_s = 3.08 m Ω and R_p = 15.38 Ω , the values of *P_{MPP}*, *V_{MPP}*, *I_{MPP}*, V_{OC} , and I_{SC} will be very close to those inserted in the INT1.

TABLE II Parameters of the Prototype

Nominal rms grid voltage	$V_s = 127$ V
Nominal utility frequency	$f = 60$ Hz
DC-Bus average voltage	V_{DC} = 220 V
DC-Bus capacitance	C_{DC} = 705 μ F
Inductance L_f (full-bridge inverter)	L_f = 5.07 mH
Internal resistance of L_f	R_{1f} = 0.2 Ω
Output impedance of the PV array in STC	R_{nv} = 3.87 Ω
$C1$ Capacitor (quadratic boost converter)	C_1 = 990 µF
Specified average voltage of the C_2 capacitor	V_{C2} = 81.5 V
C ₂ Capacitor (quadratic boost converter)	C_2 = 990 µF
Specified average current of the inductor L_1	I_{L1} = 7.67 A
Inductance L_1 (quadratic boost converter)	$L_1 = 1.5$ mH
Internal resistance of L_1	$R_{LI} = 0.18 \Omega$
Inductance L_2 (quadratic boost converter)	L_2 = 2.11 mH
Internal resistance of L_2	R_{L2} = 0.2 Ω
Duty cycle of the quadratic boost converter	$D = 0.62$
PWM converter switching frequencies	f_{sw} = 20 kHz
Sampling frequency of the P&O MPPT	$f_{S\;MPPT}=5\;Hz$
P&O voltage step size	$\Delta v = 0.5$ V
DSC Sampling frequency	$f_{S DSC}$ = 60 kHz
DAQ sampling frequency	$f_{S, DAO} = 5$ kHz

Figure 8c (INT3) presents the third interface, called "PV array characteristic curves". In the INT3, the curves $I_{PV} \times V_{PV}$ and $P_{PV} \times V_{PV}$ are plotted. They are obtained from the real information (measured values) of the solar irradiation and temperature on the PV array. With these curves, the user can observe the estimated values of the voltage (V_{MPP}) and current (I_{MPP}) of the PV array, referring to the estimated maximum power point (P_{MPP}) . It is worth mentioning that the estimated values achieved with the PV model are obtained using the measured real values of solar irradiation and temperature.

TABLE III

Fig. 8. Graphical user interface of the RTMS: (a) configurations, (b) adjustments of the series and parallel resistances of the PV cell model, (c) characteristic curves of the photovoltaic array, (d) estimated and monitored quantities of the photovoltaic array.

Fig. 9. Graphical user interface of the RTMS: (a) monitored quantities of the voltage and current injected into the grid, (b) estimated and monitored quantities.

Figure 8d shows the INT4, called "Estimated and monitored PV array quantities". In this interface, the curves referring to the values of the monitored quantities V_{PV} , I_{PV} and $P_{\rm PV}$ are plotted, as well as the quantities estimated by the model, V_{MPP} , I_{MPP} and P_{MPP} . Thus, the user can check if the power produced by the PV panel is compatible with the estimated PV power, such that the performance of the MPPT algorithm can be verified.

Figure 9a shows the interface 5 (INT5), called "Grid current and voltage". This window allows the user to see the waveforms of the grid voltage (v_s) and the current injected into the grid (i_s) . Also, the THD of both the voltage v_s and the current i_s can be analyzed. In addition, the grid apparent (S) power and active power (P) injected into the grid, as well as the PF can also be calculated.

Finally, Figure 9b shows the INT6, called "Estimated and monitored quantities". This window allows the user to see the values of all estimated and monitored magnitudes of the system. Moreover, the INT6 provides the option of storing the data obtained in a configurable time interval. The data is stored in ".txt" format, which makes it easy to use such data in other text editing programs for reporting purposes.

The efficiency of the proposed system could be achieved experimentally by comparing the results obtained using the RTMS with those obtained from the Wattmeter Y-WT3000 for the assessment of VPV, IPV, PPV, Vs (rms grid voltage) Is (rms current injected into the grid), P (Active Power) and PF (Power Factor). To measure the current THD, the power quality analyzer FLUKE F-43B was used. The curves of the following magnitudes V_{PV} , I_{PV} , P_{PV} , v_s and i_s obtained through the Wattmeter Y-WT3000 are shown in Figure 10.

All the experimental results are summarized in Table IV. Besides being an important educational tool, based on the analysis of the obtained results, the RTMS demonstrated remarkable effectiveness.

V. EDUCATIONAL METHODOLOGY BY USING THE DIDACTIC WORKBENCH

This section presents the didactic methodology and results obtained from the use of the didactic workbench shown in Figure 11. The methodology was applied to the discipline called Photovoltaic Systems, taught in both master and doctoral courses inserted in the post-graduation program in electrical engineering of UTFPR-CP, whose discipline codes are addressed as ET51K and EW43G, respectively.

The presented approach was developed through six students regularly enrolled on the course, which was given in the first semester of 2017. To carry out the classes in the laboratory, beyond to the didactic workbench, the following equipment was used: 1) computer with Maltab® software; 2) digital oscilloscope with four isolated channels (Tektronix); 3) power quality analyzer (Fluke - 43B), 4) Wattmeter (Yokogawa-WT3000), and 5) multimeters.

The students participated individually in the practical classes using the didactic workbench, where they were motivated to confront and analyze the results obtained in the experimental tests with those obtained by means of computational simulations.

After the practical activities, the students were asked about the main ease and/or difficulties they encountered during the lessons, as well as what they considered to be the added value (advance) in the learning of the contents directed to PV systems through the use of the didactic workbench.

Finally, anonymously, the students completed a form intended to evaluate the didactic workbench and the methodology used during the experimental class.

Table V presents the mean and standard deviation of the responses presented by the students according to the proposed activities (PA) using the didactic workbench in the practical classes.

Fig. 10. Experimental results - Y-WT3000 (5s/div): PV voltage (*VPV*), (4.75V/div); PV current (*IPV*), (1.875A/div); PV power (*PPV*), (35W/div); grid voltage (*vS*), (50V/div); grid current (*iS*), (1A/div).

Fig. 11. Experimental configuration of the didactic workbench: (a) overview of the didactic workbench; (b) organization and assembly of the power converters, signal conditioning boards, digital signal controller, and among others experimental hardware.

TABLE IV

The proposed activities are described as follows:

- $PA1$ From the mathematical equations (1) to (6) of the PV cell model, determine the series resistance *Rs* of the PV model, ignoring the parallel resistance *Rp*;
- PA2 Determine, in an interactive way, the values of the resistances R_s and R_p used in the mathematical PV cell model through the graphical interface of the Real Time Monitoring System (RTMS), which is integrated with the didactic workbench;
- PA3 Record the values of solar irradiance and temperature obtained in the RTMS. From the values obtained, draw the characteristic curves of the PV panel

 $(P_{PVX} V_{PV}$ and $I_{PVX} V_{PV}$. After that, compare the values of voltage, current, and power at the maximum power point (MPP) obtained both by simulation and experimentally using the RTMS;

• PA4 – Considering the DC/DC Boost converter together with the MPPT P&O-based algorithm implemented in the system, verify the behavior of the PV system for different conditions of step increments in voltage used in the MPPT algorithm. According to the recorded values of solar irradiation and temperature, evaluate by means of the theoretical curves (Matlab® software) whether the PV system is operating in the region of the MPP;

TABLE V Mean and Standard Deviation Responses Presented by the Students According to the Proposed Activities Using the Didactic Workbench in Experimental Class

- PA5 Considering that all the energy extracted from the PV panel is supplied to the grid, observe the voltages and currents of the PV array and power grid. With the values recorded, determine the efficiency of the system and analyze the quality of the current injected into the power grid;
- PA6 Considering that the PV system under study is installed in a residence with average consumption of 70 kW/month, calculate the power injected during the month, as well as the energy saving. Consider a mean solar irradiance of 70% during 8 hours of system operation per day, and a tariff cost of electric energy of R\$ 0.57 kWh/month.

Table VI presents the items used in the evaluation of the educational methodology addressed during the development of the experimental activities with the use of the didactic workbench for teaching concepts of PV systems. For each question presented, the student was required to mark his/her evaluation considering one of the four available options, as follows: A) strongly agree (100%) : B) partially agree (50%) . C) agree in part (25%) ; and D) strongly disagree (0%) .

Based on the list of questions presented in Table VI, the evaluations of the information collected from the didactic workbench, as well as the educational methodology, were analyzed. The results of this evaluation are presented as a bar chart shown in Figure 12.

The analysis was performed taking into account the calculation of the mean of each question answered by the students, according to the choice of weights given to items A, B, C, and D.

TABLE VI

Questionnaire Submitted to the Students to Evaluate the Didactic Workbench and the Methodology Used in the Experimental Classes

In general, the students perceived a better understanding regarding themes associated with photovoltaic systems. In addition, students improved their critical analysis skills after performing practical activities and demonstrated advances in understanding the topics covered in the course. During the practical classes, it was possible to observe greater involvement and participation of the students in the proposed activities. Finally, it was observed that the students presented greater motivation both during and after the accomplishment of these activities, demonstrating greater commitment to the study of the discipline, as well as enthusiasm in the discussion of themes related to topics involving PV systems.

Fig. 12. Survey results applied to the students taking into account the use of didactic workbench in experimental class.

VI. CONCLUSION

This work presented a didactic workbench, indicated to assist the teaching of PV systems addressed in topics/subjects of undergraduate and postgraduate electrical engineering courses. The system consists of a real-time monitoring system operating in conjunction with a double-stage PV system connected to the utility grid. In addition, effective and dynamic interaction with the students was supported by means of an accessible graphical user interface.

By means of a mathematical model that allows to simulate a photovoltaic cell, it was possible to compare computationally and experimentally the performance of the PV system in real-time. Thus, the proposed educational platform can also be used to assist student in projects tied to MPPT techniques.

The effectiveness of the proposed didactic workbench was evaluated in an educational environment, where it was proved to be a promising and versatile tool when applied to teaching of photovoltaic systems.

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