# FULL-BRIDGE ZVS-PWM HYBRID SWITCHED-CAPACITOR ISOLATED DC-DC CONVERTER

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Abstract - This paper presents a new hybrid switchedcapacitor (HSC) isolated DC-DC converter topology generated from the integration of the ladder switching cell with the full-bridge ZVS-PWM converter. This new topology reduces the voltage stress on the switches and other components on the primary side of the transformer to half of the bus voltage, spontaneously equalizes the voltage in the divider capacitors and presents zerovoltage-switching (ZVS) in all switches for a wide load range. The principle of operation, static gain, current stress in the power semiconductors, and commutation analysis are presented in this paper. A theoretical and experimental comparative analysis of the new topology with the TL-NPC converter is also performed. Experimental results with a laboratory prototype with 2 kW rated power, 800 V input voltage, 60 V output voltage and 100 kHz switching frequency show a maximum efficiency of 97.12% for the HSC converter against 96.49% for the TL-NPC converter.

*Keywords* – Full-bridge ZVS-PWM converter, Hybrid converter, Isolated DC-DC converter, Ladder cell, Switched-capacitor converter, Zero-voltage-switching.

## I. INTRODUCTION

The growing interest in DC distribution and transmission systems, DC microgrids, photovoltaic energy systems, storage systems, electric vehicles and auxiliary power supplies for medium and high voltage is driving the development of high efficiency DC-DC converters for medium and high voltage systems. Converters with series connected power switches [1], [2], series connected modular converters [3], [4] and multilevel converters [5]–[8] are often used for this purpose. A notable example is the three-level neutral-point-clamped (TL-NPC) DC-DC converter [5], operating at half the bus voltage on the power semiconductors and zero-voltage-switching (ZVS). However, the equalization of the voltage on the power switches and input capacitors does not occur spontaneously, being sensitive to the parametric variations of the components and to asymmetries in the command gate signals of the switches, and requiring additional control circuits to ensure voltage equalization.

Another technique traditionally employed in signal processing circuits and introduced in energy processing

systems is the use of switched-capacitor (SC) cells to process power. These SC cells promote a reduction in the voltage level on the power switches spontaneously, eliminating the need for a control circuit for this purpose. This lowering of the voltage level across the switches makes it possible to operate high voltage converters using low voltage power semiconductors. Low voltage MOSFETs have lower conduction resistance  $(R_{DSon}$  proportional to  $V_{DS}^{2.5})[9]$  and parasitic capacitances (Coss) of lower value, so their use reduces the conduction and fixed losses, consequently increasing the efficiency of the converter. Despite these advantages, this type of converter has limitations in terms of voltage control as a function of the duty cycle variation, making it necessary to use a hybrid switched-capacitor (HSC) topology formed by integrating the SC cells with the conventional converters that have inductors.

The ladder cell [10] is an SC topology that is easy to integrate with other converters. It allows the creation of hybrid topologies with lower voltage stress on the components and spontaneous equalization of the voltage division and is used in non-isolated DC-DC converters [11]–[14] and in isolated DC-DC converters [15], [16].

This paper presents a new HSC full-bridge isolated DC-DC converter topology generated from the integration of the ladder switching cell with the FB-ZVS-PWM converter [17]. This new topology preserves the characteristics of the original FB-ZVS-PWM converter and adds the advantage of spontaneous equalization of the voltage stress in the primary side power components to half the value of the bus voltage. This offers an alternative for applications that operate with high input voltage.

#### II. PROPOSED CONVERTER

The proposed converter integrates the ladder switching cell with the FB-ZVS-PWM converter, the power stage for which is shown in Figure 1.a. In this figure, the capacitors  $C_1$  and  $C_2$  represent the input capacitive divider,  $C_S$  is the switched capacitor that ensures voltage equalization in  $C_1$  and  $C_2$ ,  $S_1$  to  $S_6$  are the power switches,  $C_{C1}$  to  $C_{C6}$  represent the capacitances used in commutation,  $L_r$  is the resonant inductor used for commutation, Tr is the high frequency isolating transformer,  $D_{o1}$  and  $D_{o2}$  represent the output rectifier diodes,  $L_o$  and  $C_o$  comprise the output filter and  $R_o$  represents the load resistance. The diodes  $D_{g1}$  and  $D_{o2}$  form the input clamp circuit [18].

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Fig. 1. (a) Schematic of the proposed converter power stage and (b) power semiconductor command signals.



Fig. 2. Main waveforms of the proposed converter.

The voltage on the components of the primary circuit is equalized spontaneously and is equal to half of the bus voltage, dispensing with the need for a control circuit. This provides the new converter with a significant advantage when compared to solutions that use the series connection of power switches, series connected modular converters and multilevel converters.

Figure 1(b) shows the switch command signals. The proposed converter operates with symmetrical PWM command signals. The duty cycle D of the converter is defined as the ratio between the activation time of the gate signal of switches  $S_1$  and  $S_3$  and the switching period. The switches  $S_1, S_5$  and  $S_2, S_6$ , which form the ladder cell, are commanded by complementary signals.

## **III. PRINCIPLE OF OPERATION**

For analysis of the operation stages, the following simplifying assumptions are adopted: (a) the converter is operating in steady state; (b) MOSFETs are replaced by ideal

switches with a resistor  $R_{DSon}$  in series; (c) the magnetizing current of the transformer is considered null; (d) the inductance  $L_c$  represented in the circuit is the sum of the physical inductance  $L_r$  and the leakage inductance of the transformer primary  $L_d$ ; (e) capacitors, inductors and diodes are considered ideal; (f) the output filter is replaced by a constant current source; (g) the output stage is reflected to the primary side of the transformer; and (h) the output voltage, the rectified voltage and the output current reflected to the primary side are represented, respectively, by  $V'_o$ ,  $V'_{ret}$ and  $I'_o$ .

Figure 2 shows the main waveforms, Figure 3 the operating stages and Figure 4 the equivalent circuits for the different topological states.

#### A. First Stage of Operation $(t_0 - t_1) - [Figure 3.a]$

In this operating stage, switches  $S_1$ ,  $S_4$  and  $S_5$  are ON and  $S_2$ ,  $S_3$  and  $S_6$  are OFF. The current  $i_{Lc}$ , in absolute value, becomes smaller than the output current  $I'_{a}$ , and the four output rectifier diodes are forward biased. Thus, the current  $I'_{a}$  flows in freewheeling through the output diodes and the voltage  $V'_{ret}$  is zero. The input source  $V_{in}$  supplies energy to the capacitors, and the  $L_c$  inductor, and the current in  $L_c$ increases linearly from  $-I'_o$  until reaching the value of  $I'_o$ . Capacitors  $C_s$  and  $C_2$  are connected in parallel through switches  $S_1$  and  $S_5$ , and the peak current in these capacitors is limited by the  $R_{DSon}$  of these switches. Disregarding the voltage drop across  $R_{DSon}$ , we have  $V_{ab} = V_{Cs} = V_{C1} = V_{C2} = V_{Lc} = V_{in}/2$ .

#### *B.* Second Stage of Operation $(t_1 - t_2)$ - [Figure 3.b]

At instant  $t_1$ , the current  $i_{Lc}$  reaches  $I_o$ , and the diodes  $D_{o2}$  and  $D_{o3}$  are reverse biased. At this moment,  $V_{in}$  starts to supply energy to the load. The current  $i_{Lc}$  remains constant and equal to  $I_o$ , so the voltage drop across  $L_C$  is zero. Disregarding the voltage drop across  $R_{DSon}$ , we have  $V_{ret} = V_{ab} = V_{Cs} = V_{C1} = V_{C2} = V_{in}/2$ .

#### C. Third Stage of Operation $(t_2 - t_3) - [Figure 3.c]$

At instant  $t_2$ , switches  $S_1$  and  $S_5$  are turned OFF and  $S_2$ and  $S_6$  are turned ON. Thus, switches  $S_2$ ,  $S_4$  and  $S_6$  are conducting while  $S_1$ ,  $S_3$  and  $S_5$  are blocked. Capacitors  $C_S$ and  $C_1$  are connected in parallel through switches  $S_2$  and  $S_6$ , and the peak current in these capacitors is limited by the  $R_{DSon}$  of these switches. The current in the  $L_C$  inductor remains constant and equal to  $I_o$ , so the voltage drop across  $L_C$  is zero. Disregarding the voltage drop across  $R_{DSon}$ , we have  $V_{ret} = V_{ab} = 0V$ .

## D. Fourth Stage of Operation $(t_3 - t_4) - [Figure 3.d]$

In this operating stage, switches  $S_2$  and  $S_6$  are ON and  $S_1$ and  $S_5$  are OFF. At instant  $t_3$ , switch  $S_3$  is turned ON and  $S_4$  is turned OFF. The current  $i_{Lc}$ , in absolute value, becomes smaller than  $I_o^{\prime}$ , and the four output rectifier diodes are forward biased. Thus, the current  $I_o^{\prime}$  flows in freewheeling through the output diodes and the  $V_{ret}^{\prime}$  is zero. The current in the  $L_C$  inductor decreases linearly from  $I_o^{\prime}$ until it reaches  $-I_o^{\prime}$ . The voltage  $V_{ab}$  reverses polarity, assuming the value of  $-V_{in}/2$ .

## *E. Fifth Stage of Operation* (*t*<sub>4</sub> - *t*<sub>5</sub>) - [*Figure 3.e*]

At instant  $t_4$ , the current  $i_{Lc}$  reaches  $-I_o$ , and the diodes  $D_{o1}$  and  $D_{o4}$  are reverse biased. At this moment,  $V_{in}$  starts to supply energy to the load. The current  $i_{Lc}$  remains constant and equal to  $-I_o$ , so the voltage drop across  $L_C$  is zero. Disregarding the voltage drop across  $R_{DSon}$ , we have  $V_{ret} = V_{Cs} = V_{C1} = V_{C2} = V_{in}/2$  and  $V_{ab} = -V_{in}/2$ .

# F. Sixth Stage of Operation (t<sub>5</sub> - t<sub>6</sub>) - [Figure 3.f]

At instant  $t_5$ , switch  $S_3$  is turned OFF and  $S_4$  is turned ON. The current  $i_{Lc}$  is constant and equal to  $-I_o'$ , so the voltage drop across  $L_C$  is zero. Disregarding the voltage drop across  $R_{DSon}$ , we have  $V_{ret}' = V_{ab} = 0V$ .



Fig. 3. Operation stages: (a) First stage  $(t_0 - t_1)$ , (b) Second stage  $(t_1 - t_2)$ , (c) Third stage  $(t_2 - t_3)$ , (d) Fourth stage  $(t_3 - t_4)$ , (e) Fifth stage  $(t_4 - t_5)$  and (f) Sixth stage  $(t_5 - t_6)$ .



Fig. 4. Equivalent circuits of the operating stages: (a) First stage  $(t_0 - t_1)$ , (b) Second stage  $(t_1 - t_2)$ , (c) Third stage  $(t_2 - t_3)$ , (d) Fourth stage  $(t_3 - t_4)$ , (e) Fifth stage  $(t_4 - t_5)$  and (f) Sixth stage  $(t_5 - t_6)$ .

#### IV. THEORETICAL ANALYSIS OF THE PROPOSED CONVERTER

The theoretical analysis of the static gain, the current stress in the inductor, the capacitors and switches, and the commutation of the proposed converter are presented in the next section.

## A. Static Gain

According to the waveforms shown in Figure 2, the average output voltage is given by

$$V_o = \frac{V_{in}}{2n_{tr}} \left( D - \frac{2\Delta t_1}{T_s} \right) \tag{1}$$

where:

 $n_{tr} = N_p / N_s$ : transformer turns ratio;

 $N_p$ : number of turns of the primary winding;

 $N_s$ : number of turns of the secondary winding.

The static gain of the converter is represented by

$$q = \frac{V_o}{V_{in}} = \frac{1}{2n_{ir}} \left( D - \Delta D \right) \tag{2}$$

where the term  $\Delta D$  is represented by

$$\Delta D = \frac{2\Delta t_1}{T_s} = \frac{8f_s L_C I_o}{n_t V_{in}}$$
(3)

which denotes the duty cycle loss caused by the voltage drop across the commutation inductance  $L_c$ .

Figure 5 shows the static gain as a function of  $\Delta D$ , with the duty cycle D as a parameter. It shows that the converter presents a linear reduction of the static gain as a function of the load current, as occurs with the conventional FB-ZVS-PWM converter [19].



Fig. 5. Converter static gain as a function of duty cycle loss.

B. Current Stress on Inductor  $L_C$  and Capacitors  $C_1$ ,  $C_2$  and  $C_s$ .

From the equivalent circuits presented in Figure 4, the instantaneous currents in capacitors  $C_s$  and  $C_1$  are defined by the expressions in Table I for each operating stage. Table I also provides the set of equations for instantaneous currents in  $L_c$ , and the initial conditions for the current in

 $C_{\scriptscriptstyle S}$  , represented by  $I_{\scriptscriptstyle Cs(10)}$  to  $I_{\scriptscriptstyle Cs(60)}$  .

Considering  $C_1 = C_2 = C_s$ , we define the time constant  $\tau$  given by

$$\tau = \frac{4}{3} R_{DSon} C_S \quad . \tag{4}$$

The effective current in the inductor  $L_c$  is determined by

$$I_{Lc,ef} = I'_o \sqrt{1 - \frac{2\Delta D}{3}} .$$
 (5)

The effective currents in capacitors  $C_s$ ,  $C_1$  and  $C_2$  are obtained through (6), (7) and (8).

$$I_{Cs,ef} = \sqrt{\frac{1}{T_s}} \begin{cases} \int_{t_0}^{t_1} \left[ \dot{i}_{Cs(1)}(t) \right]^2 dt + \int_{t_1}^{t_2} \left[ \dot{i}_{Cs(2)}(t) \right]^2 dt \\ + \int_{t_2}^{t_3} \left[ \dot{i}_{Cs(3)}(t) \right]^2 dt + \int_{t_3}^{t_4} \left[ \dot{i}_{Cs(4)}(t) \right]^2 dt \\ + \int_{t_4}^{t_5} \left[ \dot{i}_{Cs(5)}(t) \right]^2 dt + \int_{t_5}^{t_6} \left[ \dot{i}_{Cs(6)}(t) \right]^2 dt \end{cases}$$
(6)

$$I_{C1,ef} = \sqrt{\frac{1}{T_s}} \begin{cases} \int_{t_0}^{t_1} \left[ i_{C1(1)}(t) \right]^2 dt + \int_{t_1}^{t_2} \left[ i_{C1(2)}(t) \right]^2 dt \\ + \int_{t_2}^{t_3} \left[ i_{C1(3)}(t) \right]^2 dt + \int_{t_3}^{t_4} \left[ i_{C1(4)}(t) \right]^2 dt \\ + \int_{t_4}^{t_5} \left[ i_{C1(5)}(t) \right]^2 dt + \int_{t_5}^{t_6} \left[ i_{C1(6)}(t) \right]^2 dt \end{cases}$$
(7)

$$I_{C2,ef} = I_{C1,ef}$$
 (8)

### C. Current Stress on Power Semiconductors

The effective currents in power semiconductors  $S_1$ ,  $S_2$ ,  $S_3$ ,  $S_4$ ,  $S_5$  and  $S_6$  are defined by the expressions (9), (10), (11), (12), (13) and (14), respectively.

$$I_{S1,ef} = \sqrt{\frac{1}{T_s}} \left\{ \int_{t_0}^{t_1} \left[ i_{Cs(1)}(t) \right]^2 dt + \int_{t_1}^{t_2} \left[ i_{Cs(2)}(t) \right]^2 dt \right\}$$
(9)

$$I_{S2,ef} = \sqrt{\frac{1}{T_s}} \begin{cases} \int_{t_2}^{t_3} \left[ i_{C_S(3)}(t) + i_{L_c(3)}(t) \right]^2 dt + \int_{t_3}^{t_4} \left[ i_{C_S(4)}(t) \right]^2 dt \\ + \int_{t_4}^{t_5} \left[ i_{C_S(5)}(t) \right]^2 dt + \int_{t_5}^{t_6} \left[ i_{C_S(6)}(t) + i_{L_c(6)}(t) \right]^2 dt \end{cases}$$

$$(10)$$

$$I_{S3,ef} = I_o \sqrt{\frac{D}{2} - \frac{\Delta D}{3}} \tag{11}$$

$$I_{S4,ef} = I_{o}^{'} \sqrt{1 - \frac{D}{2} - \frac{\Delta D}{3}}$$
(12)

$I_{S5,ef} = \sqrt{\frac{1}{T_s}} \left\{$	$\int_{t_0}^{t_1} \left[ \dot{i}_{Cs(1)}(t) + \dot{i}_{Lc(1)}(t) \right]^2 dt \\ + \int_{t_1}^{t_2} \left[ \dot{i}_{Cs(2)}(t) + \dot{i}_{Lc(2)}(t) \right]^2 dt \right]$	(13) $I_{S6,ef} = \sqrt{\frac{1}{T_s}} \begin{cases} \int_{t_2}^{t_3} [\dot{i}_{Cs(3)}(t)]^2 dt + \int_{t_3}^{t_4} [\dot{i}_{Cs(4)}(t) - \dot{i}_{Lc(4)}(t)]^2 dt \\ + \int_{t_4}^{t_5} [\dot{i}_{Cs(5)}(t) - \dot{i}_{Lc(5)}(t)]^2 dt + \int_{t_5}^{t_6} [\dot{i}_{Cs(6)}(t)]^2 dt \end{cases}$
		TABLE I
Equations for the	e Current in the Inductor <i>L</i> <sub>C</sub>	and Current in Capacitors C <sub>s</sub> and C <sub>1</sub> for Each Operating Stage
$1^{\text{st}} \text{ Stage}$ $0 < t \le t_1 = \frac{T_s \Delta D}{2}$	$i_{Lc(1)}(t) = \left(\frac{4}{T_s \Delta D}t - 1\right)I_o$	$I_{Cs(10)} = I_{o}^{'} \frac{D - \Delta D + 2f_{s}\tau \left(2 - e^{-\frac{D}{2f_{s}\tau}}\right) - \left(\frac{2f_{s}\tau}{\Delta D}\right)^{2} \left(e^{-\frac{D-\Delta D}{2f_{s}\tau}} - e^{-\frac{D}{2f_{s}\tau}}\right)}{6f_{s}\tau \left(1 - e^{-\frac{D}{2f_{s}\tau}}\right)}$ $i_{Cs(1)}(t) = I_{Cs(10)}e^{-\frac{t}{\tau}} - \frac{I_{o}^{'}}{3\Delta D} \left[4f_{s}t + \left(2f_{s}\tau - \Delta D\right)\left(1 - e^{-\frac{t}{\tau}}\right)\right]$ $i_{C1(1)}(t) = \frac{I_{Cs(10)}}{2}e^{-\frac{t}{\tau}} - \frac{I_{o}^{'}}{6\Delta D} \left[3\Delta D - 8f_{s}t + \left(2f_{s}\tau - \Delta D\right)\left(1 - e^{-\frac{t}{\tau}}\right)\right]$
$2^{nd}$ Stage $t_1 < t \le t_2 = \frac{DT_s}{2}$	$i_{Lc(2)}(t) = I_o'$	$I_{C_{S}(20)} = I_{C_{S}(10)} e^{-\frac{\Delta D}{2f_{s}\tau}} - \frac{I_{o}}{3\Delta D} \left[ 2\Delta D + \left(2f_{s}\tau - \Delta D\right) \left(1 - e^{-\frac{\Delta D}{2f_{s}\tau}}\right) \right]$ $i_{C_{S}(2)}(t) = I_{C_{S}(20)} e^{-\left(\frac{t}{\tau} - \frac{\Delta D}{2f_{s}\tau}\right)} - \frac{I_{o}}{3} \left[1 - e^{-\left(\frac{t}{\tau} - \frac{\Delta D}{2f_{s}\tau}\right)}\right]$ $i_{C_{1}(2)}(t) = \frac{I_{C_{S}(20)}}{2} e^{-\left(\frac{t}{\tau} - \frac{\Delta D}{2f_{s}\tau}\right)} + \frac{I_{o}}{6} \left[2 + e^{-\left(\frac{t}{\tau} - \frac{\Delta D}{2f_{s}\tau}\right)}\right]$
$3^{rd}$ Stage $t_2 < t \le t_3 = \frac{T_s}{2}$	$i_{Lc(3)}(t) = I_o$	$I_{Cx(30)} = I_{o}^{'} \frac{\Delta D (D - \Delta D) - (2f_{s}\tau)^{2} e^{\frac{\Delta D - 1}{2f_{s}\tau}} + \left[ (2f_{s}\tau)^{2} + 4f_{s}\tau\Delta D \right] e^{-\frac{1}{2f_{s}\tau}} - f_{s}\tau\Delta D \left( 6 - 4e^{\frac{D - 1}{2f_{s}\tau}} \right)}{6f_{s}\tau\Delta D \left( 1 - e^{\frac{D - 2}{2f_{s}\tau}} \right)}$ $i_{Cx(3)}(t) = I_{Cx(30)} e^{-\frac{t}{\tau} \frac{D}{2f_{s}\tau}}$ $i_{C1(3)}(t) = -\frac{I_{Cx(30)}}{2} e^{-\frac{t}{\tau} \frac{D}{2f_{s}\tau}}$
4 <sup>th</sup> Stage $t_3 < t \le t_4 = \frac{T_s}{2} (1 + \Delta D)$	$i_{Lc(4)}(t) = \left[\frac{-4}{T_s \Delta D}(t - t_3) + 1\right] I_o'$	$I_{Cs(40)} = I_{Cs(30)}e^{\frac{1-D}{2f_{r}\tau}} + I_{o}'$ $i_{Cs(4)}(t) = I_{Cs(40)}e^{-\left(\frac{t}{\tau}-\frac{1}{2f_{r}\tau}\right)} + \frac{I_{o}'}{3\Delta D} \left\{ 2 - 4f_{s}t - \left(2f_{s}\tau - \Delta D\right) \left[ 1 - e^{-\left(\frac{t}{\tau}-\frac{1}{2f_{r}\tau}\right)} \right] \right\}$ $i_{C1(4)}(t) = -\frac{I_{Cs(40)}}{2}e^{-\left(\frac{t}{\tau}-\frac{1}{2f_{r}\tau}\right)} + \frac{I_{o}'}{6\Delta D} \left\{ 4 + 3\Delta D - 8f_{s}t + \left(2f_{s}\tau - \Delta D\right) \left[ 1 - e^{-\left(\frac{t}{\tau}-\frac{1}{2f_{r}\tau}\right)} \right] \right\}$
5 <sup>th</sup> Stage $t_4 < t \le t_5 = \frac{(D+1)T_s}{2}$	$i_{Lc(5)}(t) = -I_o$	$I_{C_{S}(50)} = I_{C_{S}(40)} e^{-\frac{\Delta D}{2f_{s}\tau}} - \frac{I_{o}}{3\Delta D} \left[ 2\Delta D + \left(2f_{s}\tau - \Delta D\right) \left(1 - e^{-\frac{\Delta D}{2f_{s}\tau}}\right) \right]$ $i_{C_{S}(5)}(t) = I_{C_{S}(50)} e^{-\left(\frac{t}{\tau} - \frac{1+\Delta D}{2f_{s}\tau}\right)} - \frac{I_{o}}{3} \left[1 - e^{-\left(\frac{t}{\tau} - \frac{1+\Delta D}{2f_{s}\tau}\right)}\right]$ $i_{C_{1}(5)}(t) = -\frac{I_{C_{S}(50)}}{2} e^{-\left(\frac{t}{\tau} - \frac{1+\Delta D}{2f_{s}\tau}\right)} - \frac{I_{o}}{6} \left[2 + e^{-\left(\frac{t}{\tau} - \frac{1+\Delta D}{2f_{s}\tau}\right)}\right]$
$6^{\text{th}}$ Stage $t_5 < t \le t_6 = T_s$	$i_{Lc(6)}(t) = -I_{o}$	$I_{Cs(60)} = I_{Cs(50)} e^{\frac{D-\Delta D}{2f_s \tau}} + \frac{J_o}{3} \left( 2 + e^{\frac{D-\Delta D}{2f_s \tau}} \right)$ $i_{Cs(6)}(t) = I_{Cs(60)} e^{-\left(\frac{t}{\tau} - \frac{1+D}{2f_s \tau}\right)}$ $i_{Cl(6)}(t) = -\frac{I_{Cs(60)}}{2} e^{-\left(\frac{t}{\tau} - \frac{1+D}{2f_s \tau}\right)}$



Fig. 6. Normalized effective current in semiconductors as a function of  $f_s \tau$ , with the duty cycle *D* as a parameter.

Figure 6 shows the effective currents in the power semiconductors normalized by  $I_o$  and as a function of  $f_s \tau$ , with the duty cycle D as a parameter. It can be observed that the effective currents in  $S_1$  and  $S_2$  decrease exponentially with an increase in  $f_s \tau$ . Also, the effective currents at  $S_3$ and  $S_4$  are not dependent on the  $f_s \tau$  factor and the effective currents at  $S_5$  and  $S_6$  are practically constant for  $f_s \tau > 0.3$ . The normalized effective current in semiconductors is defined by

$$\overline{I_{S,ef}} = \frac{I_{S,ef}}{I_o} \quad . \tag{15}$$

#### D. Normalized Equivalent Resistance of Equivalent Circuit

The total conduction losses, considering the six power semiconductors, are determined by (16).

$$P_{S,total} = R_{DSon} \left( I_{S1,ef}^{2} + I_{S2,ef}^{2} + I_{S3,ef}^{2} + I_{S4,ef}^{2} + I_{S5,ef}^{2} + I_{S6,ef}^{2} \right)$$
(16)

The equivalent resistance considered for determining the conduction losses in the switches is obtained by

$$R_{eq} = \frac{P_{S,total}}{\left(I_o\right)^2} \,. \tag{17}$$

The equivalent resistance normalized by  $R_{DSon}$  is defined by

$$\overline{R_{eq}} = \frac{R_{eq}}{R_{DSon}} \quad . \tag{18}$$

Figure 7.a shows the equivalent circuit considered for determining the conduction losses in the switches and Figure 7.b shows the normalized equivalent resistance curves as a function of  $f_s \tau$ , for different values of the duty cycle D. It can be observed that for  $f_s \tau < 0.3$  the equivalent resistance increases exponentially, increasing the conduction losses in the power semiconductors, and for  $f_s \tau > 0.3$  this resistance remains practically constant. For this reason, when selecting the values for the converter parameters,  $f_s \tau \approx 0.3$  is adopted.



Fig. 7. (a) Equivalent circuit for determining conduction losses in power semiconductors and (b) normalized equivalent resistance.

#### V. COMMUTATION ANALYSIS

Each pair of switches has a linear commutation occurring at constant current equal to  $I_o$ , and a resonant commutation depending on the energy stored in  $L_c$ . To obtain soft switching over a wide range of load current, it is necessary to increase the value of  $L_c$ , which in turn causes a reduction in the value of the effective duty cycle and an increase in the conduction losses. Thus, to optimize the efficiency of the converter, there is a trade-off between the soft switching range and conduction losses.

The commutation of switches  $S_1$ ,  $S_5$  and  $S_2$ ,  $S_6$  occurs at a current in the capacitors  $C_C$  equal to a quarter of the current of the inductor  $L_C$ , while the commutation of switches  $S_3$  and  $S_4$  occurs at a current equal to half the current of the inductor  $L_C$ . The resonant commutation of switches  $S_1$ ,  $S_5$  and  $S_2$ ,  $S_6$  is considered the most critical since it defines the longest dead time necessary to ensure ZVS. For each switching stage, there are two topological states, one where the voltage transition occurs in the switching capacitors  $C_C$  and another from when the switch body diode starts to conduct until the corresponding switch is commanded to conduct with ZVS. Figures 8 to 11 show the two topological states of each commutation.



Fig. 8. Resonant commutation stages of switches  $S_1$ ,  $S_2$ ,  $S_5$  and  $S_6$ : (a) voltage transition stage over the commutation capacitors and (b) body diode conduction stage.



Fig. 9. Linear commutation stages of switches  $S_1$ ,  $S_2$ ,  $S_5$  and  $S_6$ : (a) voltage transition stage over the commutation capacitors and (b) body diode conduction stage.

Figure 12 shows the main waveforms for commutation analysis, highlighting the resonant and linear commutation transients for each pair of switches. The resonant transitions are represented by  $\Delta t_{r1}$  and  $\Delta t_{r2}$ , the linear transitions by  $\Delta t_{l1}$  and  $\Delta t_{l2}$ , and the dead time by  $t_{d1}$  to  $t_{d4}$ .



Fig. 10. Resonant commutation stages of switches  $S_3$  and  $S_4$ : (a) voltage transition stage over the commutation capacitors and (b) body diode conduction stage.



Fig. 11. Linear commutation stages of switches  $S_3$  and  $S_4$ : (a) voltage transition stage over the commutation capacitors and (b) body diode conduction stage.

Table II presents a summary of the switching times, dead time and the design constraints equations used to obtain the ZVS.

Commutation	Constraints for ZVS	Time interval	Equation
Resonant	$I_{o,zvs1} \ge \sqrt{\frac{4C_C}{L_C}} \frac{V_{in}}{2}$	$\Delta t_{r1}$	$\Delta t_{r1} = \left[\frac{\pi}{2} - \cos^{-1}\left(\frac{V_{in}}{2I_o^{\prime}}\sqrt{\frac{4C_c}{L_c}}\right)\right]\sqrt{4L_cC_c}$
$S_1, S_2, S_5$ and $S_6$ .	and $\Delta t_{r1} < t_{d1} < t_{d1(\max)}$	$t_{d1(\max)}$	$t_{d1(\text{max})} = \Delta t_{r1} + \frac{2L_C \dot{I_{o,\text{zvs1}}}}{V_{in}} \cos\left(\frac{1}{\sqrt{4L_C C_C}} \Delta t_{r1}\right)$
Linear $S_1, S_2, S_5$ and $S_6$ .	$t_{d2} > \Delta t_{l1}$	$\Delta t_{l1}$	$\Delta t_{I1} = \frac{2C_C V_{in}}{I_o}$
Resonant $S_3$ and $S_4$ .	$I_{o,zvs2}' \ge \sqrt{\frac{2C_C}{L_C}} \frac{V_{in}}{2}$ and $\Delta t_{r2} < t_{d3} < t_{d3(max)}$	$\Delta t_{r2}$	$\Delta t_{r2} = \left[\frac{\pi}{2} - \cos^{-1}\left(\frac{V_{in}}{2I_o}\sqrt{\frac{2C_c}{L_c}}\right)\right]\sqrt{2L_cC_c}$ $t_{d3(\max)} = \Delta t_{r2} + \frac{2L_cI_{o,zvs2}}{V_{in}}\cos\left(\frac{1}{\sqrt{2L_cC_c}}\Delta t_{r2}\right)$
Linear $S_3$ and $S_4$ .	$t_{d4} > \Delta t_{l2}$	$\Delta t_{l2}$	$\Delta t_{12} = \frac{C_c V_{in}}{I_o}$

 TABLE II

 Summary with Equations for Switching Times, Dead Time and Constraints for ZVS



Fig. 12. Main waveforms for commutation analysis.

## VI. THEORETICAL ESTIMATE OF LOSSES AND EFFICIENCY

Figure 13 shows the curves for the total conduction losses in power semiconductors as a function of  $f_s \tau$  for different values of D. It can be noted that for  $f_s \tau < 0.3$  the conduction losses increase exponentially and for  $f_s \tau > 0.3$ they remain practically constant. Also, as the value of D increases these losses decrease. In this study,  $f_s \tau = 0.316$ and D = 0.92 were adopted.



Fig. 13. Total conduction losses in power semiconductors as a function of  $f_e \tau$ , with the duty cycle *D* as a parameter.

Figure 14 shows the theoretical estimate of the losses distribution and efficiency of the HSC and NPC converter considering the specifications and components presented, respectively, in Tables III and IV. Compared with the NPC, the HSC converter has 0.89 W less losses in the MOSFETs and 5.52 W less in the output voltage clamping circuit, being consequently 0.3% more efficient.



Fig. 14. Theoretical losses distribution in the converters: (a) HSC and (b) NPC.

#### VII. EXPERIMENTAL RESULTS

In order to validate the theoretical analysis of the proposed topology, a laboratory prototype was designed, built and tested. Its specifications are detailed in Table III.

The prototype was conceived to be reconfigurable, working as the HSC converter or as the NPC converter on the same printed circuit board.

A photograph of the prototype power stage is shown in Figure 15.

Figure 16 shows the respective schematic, configurable for the HSC or NPC converter.

Table IV provides a list of the components used in the construction of the power stage of the converter.

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<b>Converter Specifications</b>				
Parameter	Symbol	Value		
Input voltage	$V_{in}$	800 V		
Output voltage	$V_o$	60 V		
Rated output power	$P_o$	2 kW		
Switching frequency	$f_s$	100 kHz		
ZVS range	$P_{o,ZVS}$	$>40\% P_o$		
Duty cycle loss	$\Delta D$	14%		



Fig. 15. Photograph of the laboratory prototype power stage in the HSC converter configuration.



Fig. 16. Power stage schematic with HSC and NPC converter configuration options.

	TABLE IV	
	Components Used in the Pr	ototype
Reference	Description	Part Number
$S_1 - S_6$	SiC MOSFET 21 A / 650 V	SCT3120AL
$D_{g1}, D_{g2}$	Ultrafast diode 4 A / 600 V	MUR460
$D_{C1}, D_{C2}$	Ultrafast diode 4 A / 600 V	MUR460
$D_{o1}, D_{o2}$	Schottky diode 40 A / 250 V	MBR40250TG
$C_1, C_2, C_S$	Film capacitor 15 µF / 650 V	C4AQCBU5150A12J
$C_{C1}$ - $C_{C6}$	Ceramic capacitor 150 pF / 1 kV	F151K25Y5RN63J5R
$C_d$	Film capacitor 4.7 µF / 650 V	-
$C_o$	Electrolytic capacitor 430 µF /	UBY2A431MHL
	100V	
$C_{g1}, C_{g2}$	Capacitor 3.3 nF (for HSC)	-
	Capacitor 9 nF (for NPC)	
$R_{g1}, R_{g2}$	Resistor 68 k $\Omega$ / 3 W (for HSC)	-
	Resistor 13.7 kΩ (for NPC)	
Tr	Core Thornton NEE-65/33/39	NEE-65/33/39 - 7200
	$N_p = 26 \text{ turns} (220 \text{ x} 38 \text{ AWG})$	
	$N_{s1} = N_{s2} = 5$ turns (880 x 38AWG)	
	$n_{tr} = 5.2$	
	Leakage inductance $(L_d) = 8 \mu H$	
$L_r$	Inductor $L_r$ : 14 µH	MMT140EE3007
	N = 9 turns (220 x 38 AWG)	
	Air gap (lg) = 0.44  mm	
Lo	Inductor $L_o$ : 12.65 µH	MMT140EE4215
	<i>N</i> = 8 turns (880 x 38 AWG)	
	Air gap $(lg) = 1.15 \text{ mm}$	
PCB	FR4 / 2oz / 240 x 215 x 1.6 mm	FB-ZVS-PWM-HSC

Figure 17.a shows that the output characteristics of the HSC and NPC converters are identical, with a linear drop in the output voltage as a function of the load current.

Figure 17.b shows the voltage across the voltage divider capacitors  $C_1$  and  $C_2$  as a function of the output power. It can be observed that, for the HSC converter, the voltages on the capacitors remain naturally equalized for the entire output power range, while, for the NPC, the voltages on the capacitors are unbalanced and vary with the power, reaching a difference of up to 40 V.

The effect of the asymmetry of the command signals of the switches on the voltage balance in capacitors  $C_1$  and  $C_2$ was also evaluated by numerical simulation. It was verified that, for the NPC, a difference of 5% between the command signals causes an unbalance of 20 V in capacitors  $C_1$  and  $C_2$ . While, for the HSC, the voltages on the capacitors remain balanced.



Fig. 17. (a) Output characteristic of the HSC and NPC converter and (b) voltage across capacitors  $C_1$  and  $C_2$  as a function of output power.

Figure 18 shows the efficiency curve as a function of the output power  $P_o$  for the HSC and NPC converters. It can be noted that the HSC converter presents a maximum efficiency of 97.12% at 816 W output power, while the NPC reaches 96.49% at 1150 W output power. The HSC converter presents higher efficiency than the NPC for the entire power range between 240 W and 2 kW. This higher efficiency of the HSC is mainly because it allows the use of a regenerative clamping circuit on the primary side of the converter, thus reducing the losses in the clamping circuit of the output diodes.



Fig. 18. Efficiency curves for HSC and NPC converters.

The losses in the output voltage clamping circuit were 772 mW for the HSC converter and 5.16 W for the NPC converter. Added to this is the fact that the HSC converter operates with lower conduction losses in the input power semiconductors (switches and diodes), as shown in Figure 19.

Figures 20 and 21 show, respectively, the typical waveforms during the commutation of the power semiconductors of the HSC and NPC, and the soft commutation threshold of each of them.



Fig. 19. Total conduction losses in the input semiconductors of the HSC converter and the NPC converter.



Fig. 20. Experimental results for the soft commutation threshold of each switch of the HSC converter: (a) commutation  $S_1$ , (b) commutation  $S_2$ , (c) commutation  $S_3$ , (d) commutation  $S_4$ , (e) commutation  $S_5$  and (f) commutation  $S_6$ .



Fig. 21. Experimental results for the soft commutation threshold of each switch of the NPC converter: (a) commutation  $S_3$ , (b) commutation  $S_4$ , (c) commutation  $S_5$  and (d) commutation  $S_6$ .

TABLE V
<b>Comparison of the Theoretical and Experimental ZVS</b>
Threshold

HSC				
Theoretical	Experimental	Error		
34.7%	40.5%	16.7%		
21.1%	24.0%	13.7%		
33.4 %	32.0%	4.2%		
10.5%	10.5%	0.0%		
34.7%	40.5%	16.7%		
21.1%	24.0%	13.7%		
Ν	PC			
Theoretical	Experimental	Error		
21.2%	27.0%	27.4%		
21.2%	28.4%	34.0%		
21.2%	32.2%	51.9%		
21.2%	32.2%	51.9%		
	H Theoretical 34.7% 21.1% 33.4% 10.5% 34.7% 21.1% Theoretical 21.2% 21.2%	HSC           Theoretical         Experimental           34.7%         40.5%           21.1%         24.0%           33.4]%         32.0%           10.5%         10.5%           34.7%         40.5%           21.1%         24.0%           34.7%         40.5%           21.1%         24.0%           Theoretical Experimental           21.2%         27.0%           21.2%         28.4%           21.2%         32.2%		

Table V shows a comparison between the theoretical and experimental values of the ZVS threshold for the HSC and NPC converters. It represents the minimum values in terms of the percentage of rated output power that ensures ZVS. The theoretical values for the HSC converter were calculated considering a dead time of 200 ns. It can be seen that the theoretical and experimental values for the HSC converter are very close, with a maximum error of 16.7%, thus validating the theoretical analysis performed.

The experimental results show that the HSC converter presents soft commutation in all switches from 810 W of output power (40.5% of the rated power) and the NPC from 644 W (32.2% of the rated power). It is also observed that switches  $S_2$ ,  $S_4$ , and  $S_6$  of the HSC converter have a wider soft commutation range than the switches of the NPC converter.

## VIII. CONCLUSIONS

A new isolated DC-DC converter topology, generated through the integration of the full-bridge converter with the switched-capacitor ladder cell, with reduced voltage on the switches, was proposed, analyzed, dimensioned and tested in the laboratory. The experimental results validated the theoretical analysis. A comparative analysis of the proposed HSC converter with the NPC converter showed that the HSC has the advantages of spontaneous voltage equalization on the capacitors, lower conduction losses, it allows voltage clamping in the transformer primary side, and it is easy to expand to more voltage levels. On the other hand, the NPC converter presents a wider ZVS range and a smaller number of switches.

The main features of the new converter are:

- spontaneous voltage equalization in the capacitors;
- the input stage components are subjected to half the bus voltage;
- it allows generalization to divide the voltage into more levels;
- it allows the use of a simple, non-dissipative voltage clamper in the primary side;
- a wide range of soft commutation is possible; and
- high efficiency can be achieved.

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